

Introduction to Sensors

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Motivation – why we talk about sensors

- **Data-centric ML**
 - The **importance of quality** data sets
 - So far, we have mainly looked at human-generated data (voice, photography, social media ..)
but there is a whole other class of data, which is generated through **scientific measurement**.
 - Its importance e.g. in Environmental Science, Earth Observation, Energy transition, Climate Change, Logistics, Buildings, Urban Planning, Agriculture, Aquaculture, ... to name a few.

Sensors / Definition I

- A sensor is a device, module, or subsystem that **transforms a property of the physical (“real”) world to a signal that can be read by electronic/digital systems - to “data”.**
- Properties, in the widest sense, can be **events, changes, states/static properties.**
- There are many possible (and conflicting) definitions.
Does a plant have sensors? (Shown on title slide: Drosera rotundifolia)

Sensors / Definition II

Note terms that might be problematic:

real world,

physical world

“to translate into data” -

data is not inherently there – it is a human construct,
created under technical, social, cultural conditions

Sensors / Definition IV

Clarification:

we will distinguish between the

the sensor -



and the

full **sensor node**, which includes a **sensor** and an

embedded system, a board, a device

(with processor/MCU, memory, storage, I/O,

on-board communications, networks, etc)

both of which together make up the

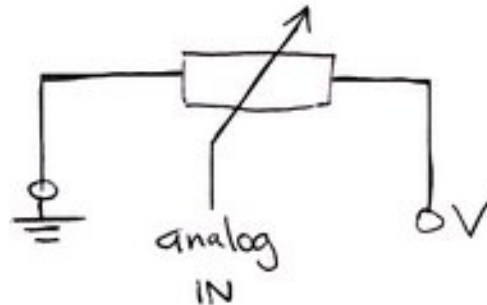
sensor node or device.



In practice, we often find the term **sensor** to denote the whole system, e.g. a *WiFi CO2 sensor, LoRa watermeter*.

Sensors / Principle

- A sensor typically transforms a “real world” property into a **voltage** (or current, which then gets converted to a voltage) which then may be digitized.
- Some **physical effect** is needed to make that transformation.
- To that end, for experiments, a voltage source with a potentiometer fully replaces any type of (analog) sensor.



Sensors / Classification, types

- **Analog / Digital**

the output is an analog voltage or already digital (→ ADC)

- **Active / Passive**

with regards to the measurement – does the sensor impact the object of interest? Discuss e.g. light sensors, watermeters

- **Powered / Non-powered**

– do we need to power the sensor in order for it to work?

- **Physical / Chemical / Biological**

- Field readiness, autonomy

- Cost: low-cost vs. (expensive) lab grade sensors

Sensors / Overview I

Push Button

Displacement

Pressure, weight, bend, vibration

Distance

Proximity

Position

Motion

Acceleration

Orientation (Magnetic, Gyroscope)

Hall/Reed

Voltage / Current

RF Intensity

Light

Sound

Pressure, barometer

Temperature Humidity, soil moisture

Wind (speed, direction)

Radioactivity

Water

→ Level, flow, chemistry

Air

→ indoor/outdoor

→ gaseous / particulate

→ Smoke, Fire

Biological / Health

→ heart, pulse, breath, eye, ...

Sensors / Reminder of prerequisites

- SI UNIT system
- Powers of ten

International System of Units (SI)

SI Base Units

Base Quantity	Name	Symbol
Length	meter	m
Mass	kilogram	kg
Time	second	s
Electric current	ampere	A
Temperature	kelvin	K
Amount of substance	mole	mol
Luminous intensity	candela	cd

SI Derived Units

Derived Quantity	Name	Symbol	Equivalent SI units
Frequency	hertz	Hz	s ⁻¹
Force	newton	N	m·kg·s ⁻²
Pressure	pascal	Pa	N/m ²
Energy	joule	J	N·m
Power	watt	W	J/s
Electric charge	coulomb	C	s·A
Electric potential	volt	V	W/A
Electric resistance	ohm	Ω	V/A
Celsius temperature	degree Celsius	°C	K*

*Unit degree Celsius is equal in magnitude to unit kelvin.

SI Prefixes

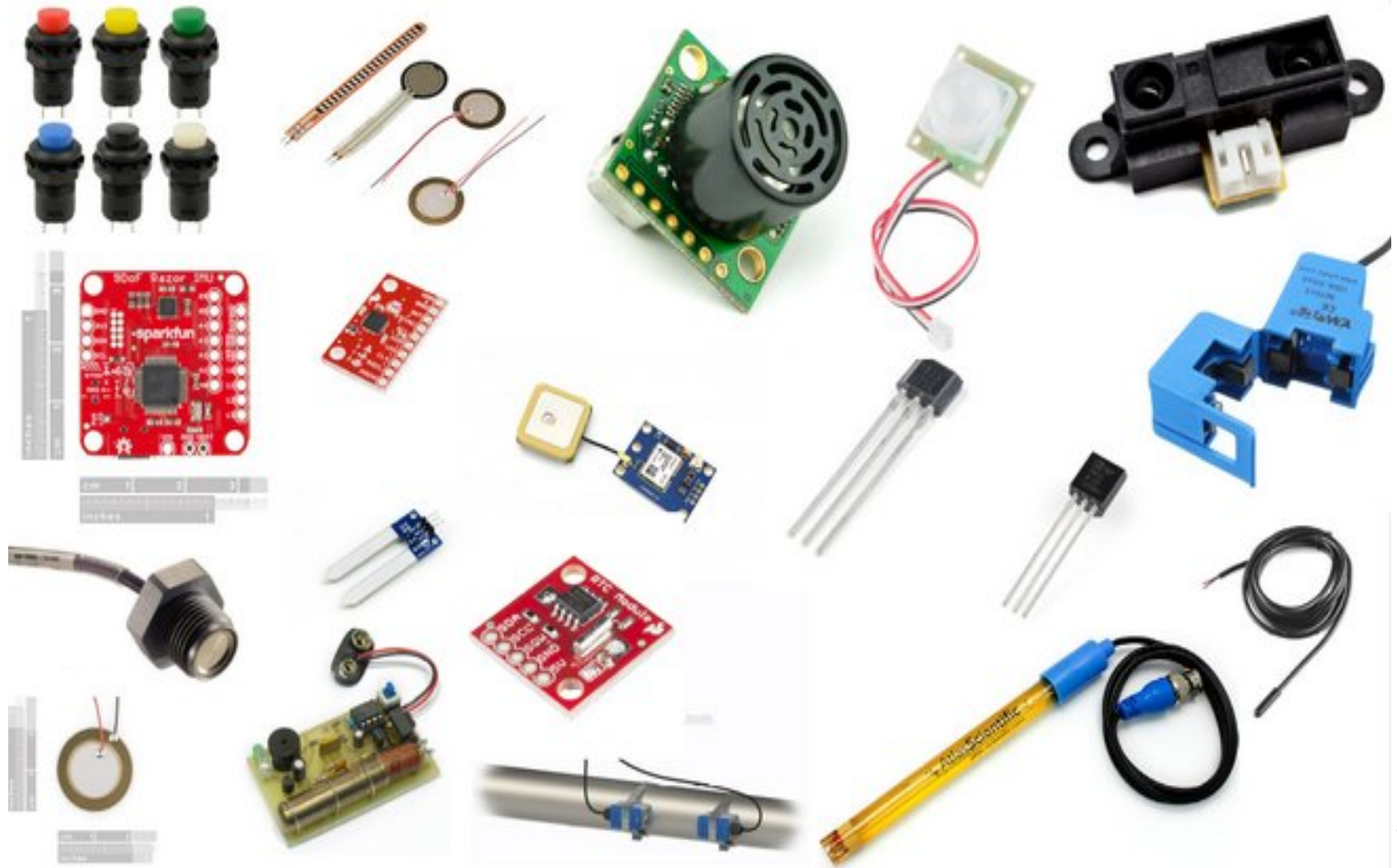
Factor	Name	Symbol	Numerical Value
10 ¹²	tera	T	1 000 000 000 000
10 ⁹	giga	G	1 000 000 000
10 ⁶	mega	M	1 000 000
10 ³	kilo	k	1 000
10 ²	hecto	h	100
10 ¹	deka	da	10
10 ⁻¹	deci	d	0.1
10 ⁻²	centi	c	0.01
10 ⁻³	milli	m	0.001
10 ⁻⁶	micro	μ	0.000 001
10 ⁻⁹	nano	n	0.000 000 001
10 ⁻¹²	pico	p	0.000 000 000 001

* Adapted from MET Special Publication 811
 * SI rules and style conventions recommend using spaces rather than commas to separate groups of three digits.

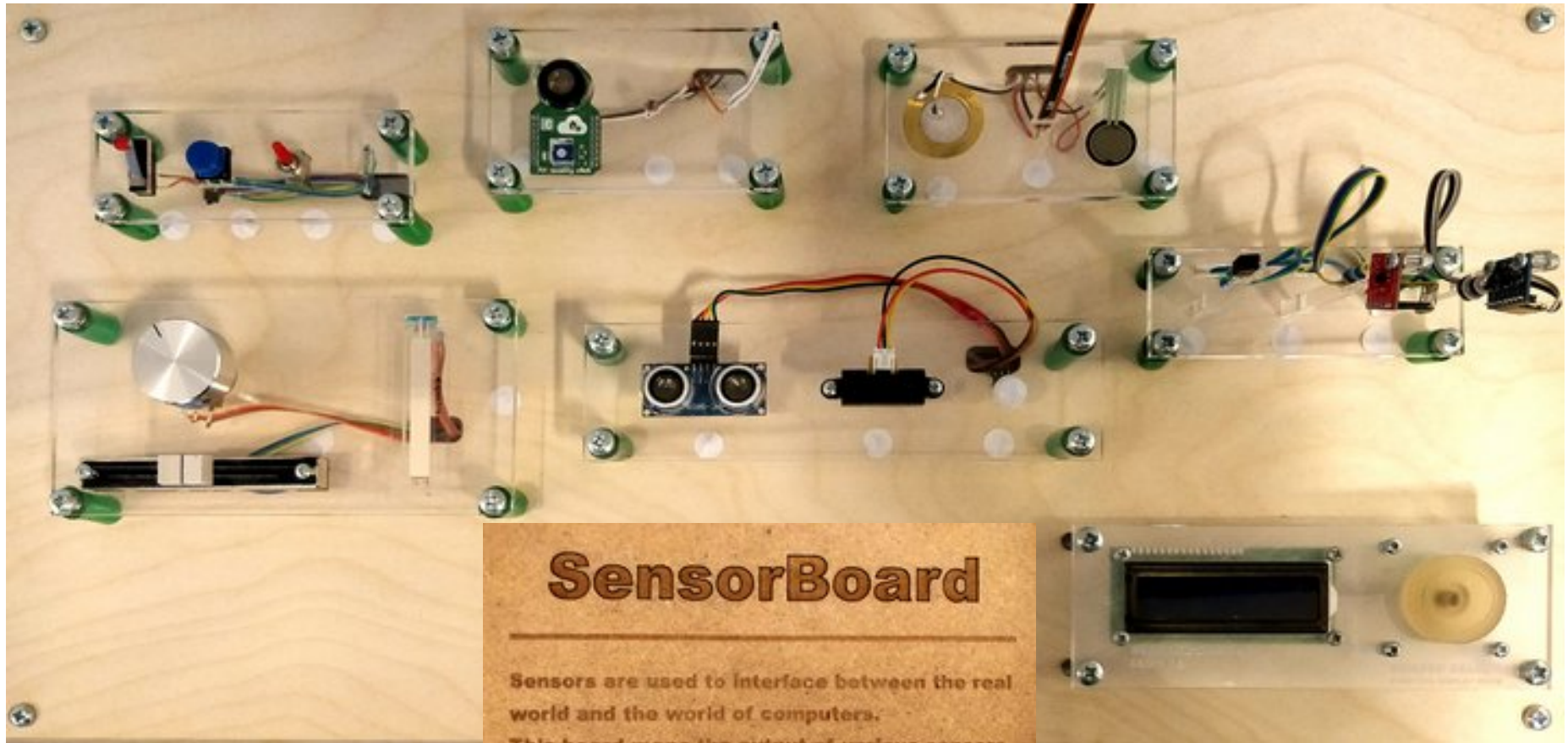


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 AP6809

What sensors look like



Sensors / Overview II



SensorBoard

Sensors are used to interface between the real world and the world of computers.

This board maps the output of various sensors to a numeric display, providing an insight into what data to expect from a given sensor.

ixD LAB

source: ixdlab.itu.dk

Sensors / Simple examples





Physical principle

Mechanical, closing circuit

Applications

human interaction

Sensors / Mobile Phone



Physical principle

Piezo effect

Applications

Force

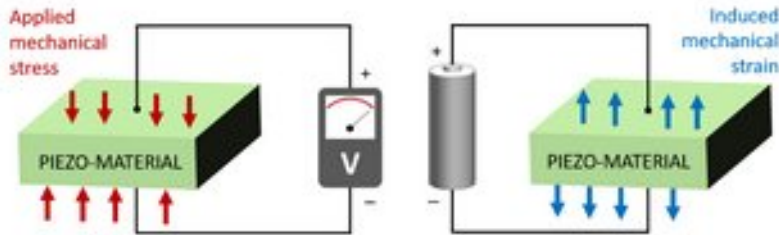
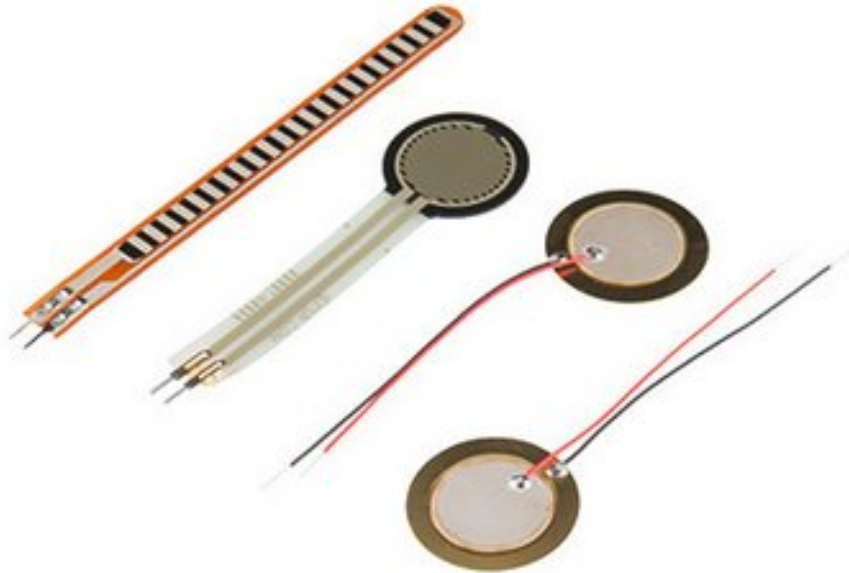
Motion

Bending

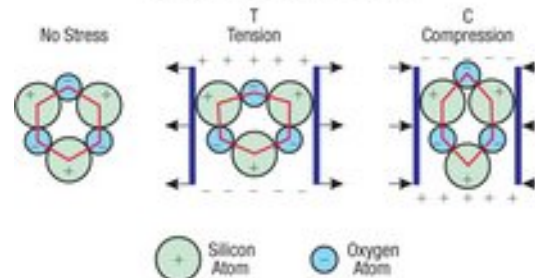
Moving

Vibration

Audio



Piezoelectric Effect in Quartz



Physical principle

Piezo, Mems, other

Applications

Sound :)



Sensors / Distance / Ultrasonic



source: sparkfun

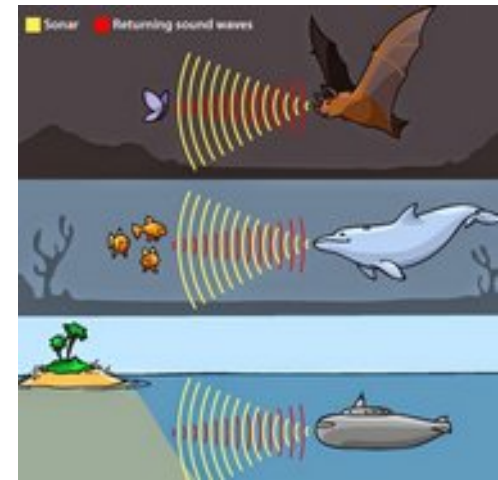
Physical principle

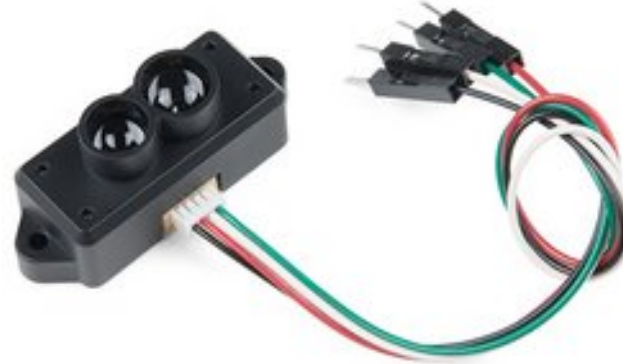
Speed of sound

Applications

Distances

e.g. liquid levels





Physical principle

Triangulation

Time of Flight (TOF)

Interferometry

Applications

Distances



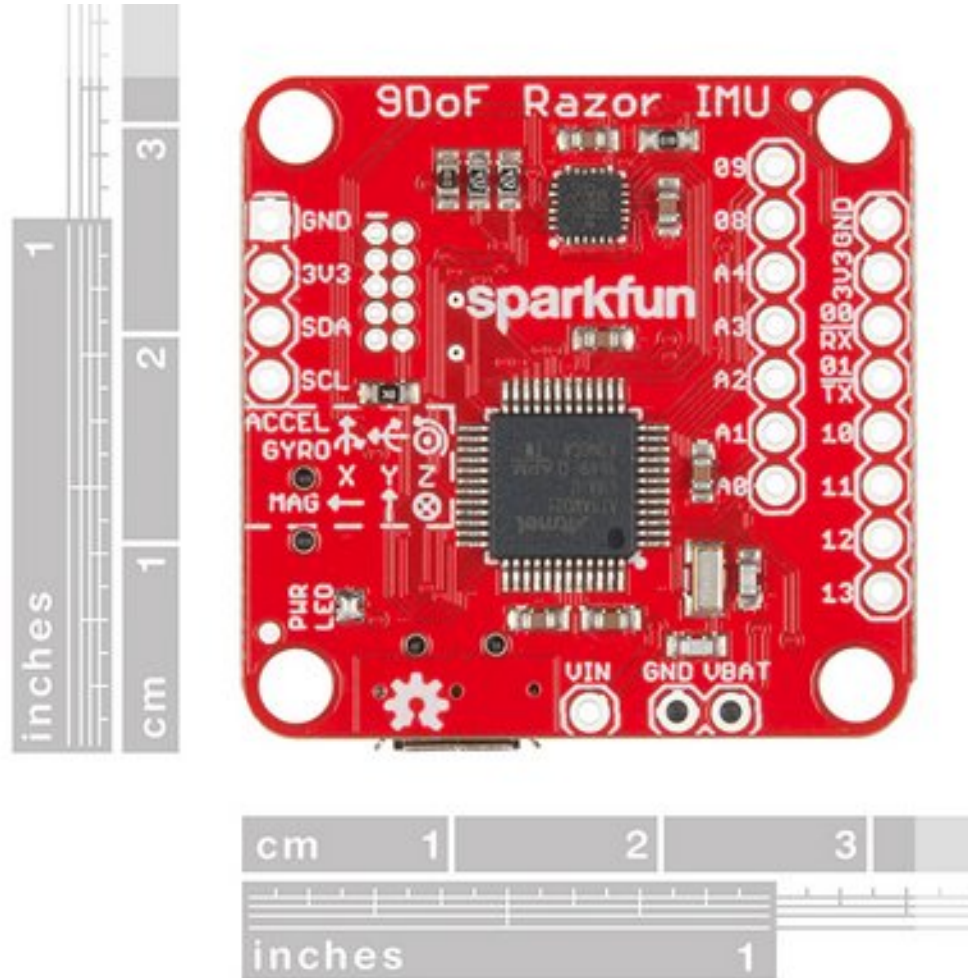
Physical principle

Reflection

Applications

Proximity

Sensors / Acceleration, Orientation



Physical principle

MEMS

MicroElectroMechanical

Applications

Acceleration

Motion

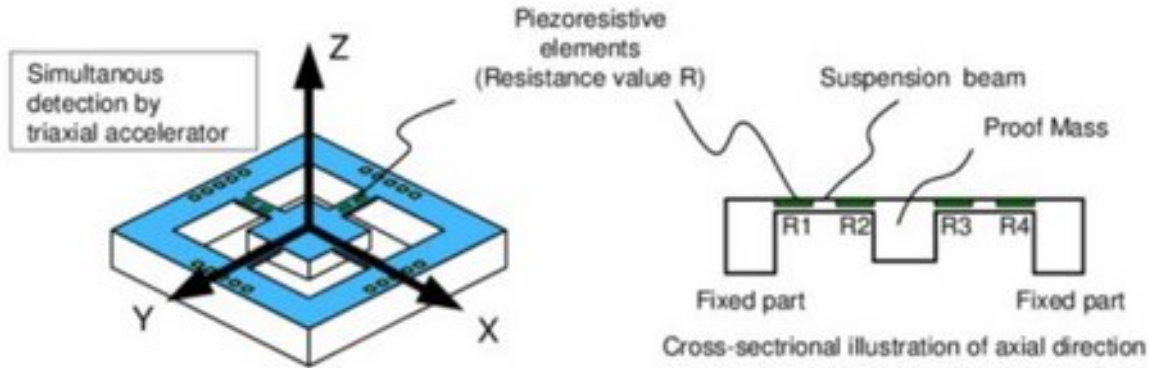
Orientation

Gyroscope

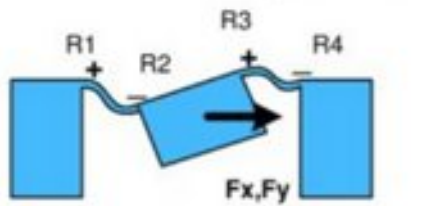
(angular motion)

Compass

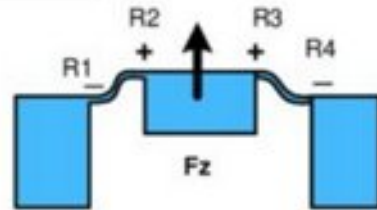
Sensors / Acceleration



A full bridge circuit formed by 4 piezoresistors that detects unbalanced voltage



Cross-sectional view of change in X or Y axes



Cross-sectional view of change in Z axes

Physical principle

MEMS

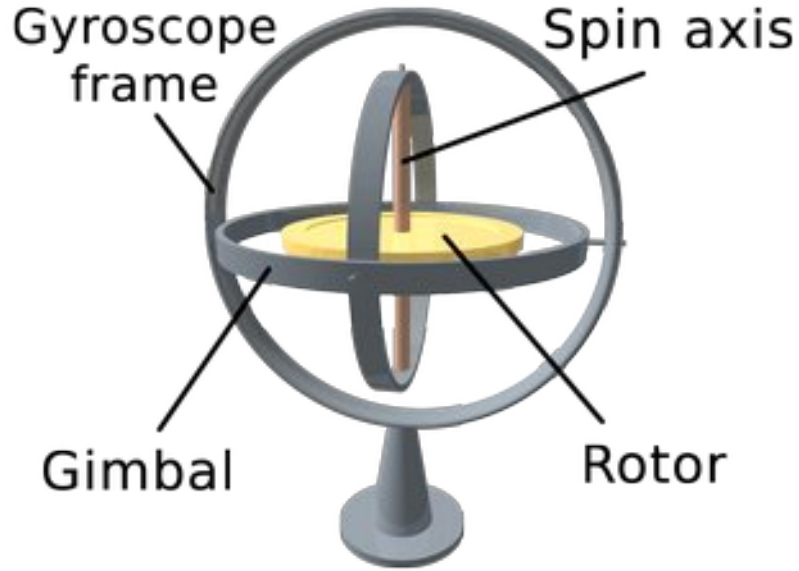
MicroElectroMechanical
Sensors

Applications

Acceleration

source: Liu, R., Zhang, Z., Zhong, R., Chen, X., & Li, J. (2007). Nanotechnology synthesis study: research report. Texas Department of Transportation.

Sensors / Gyrometer



Physical principle

MEMS

MicroElectroMechanical

Sensors

Applications

Motion

Orientation

Gyroscope

(angular motion)

Physical principle

Hall effect

Applications

Magnetic fields

→ Motion





Physical principle

Induction

Applications

Power

Current

Sensors / Temperature



Physical principle

thermoelectric

Applications

Ambient temperature

Sensors / Liquid levels



Physical principle

resistive
barometric

Applications

Liquid levels,
technical,
environmental

Sensors / Soil moisture

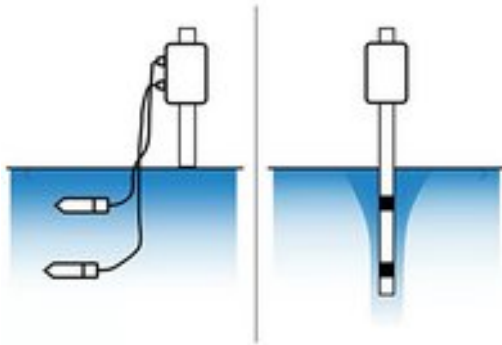
Physical principle

Resistance

Capacity

TDT (time domain transmission)

a.o.





Physical principle

Photoresistance

Applications

Light :)



Physical principle

Ionization

Geiger counter

Applications

Radioactivity

Gamma rays

→ safecast.net





Physical principle

Turbine

Ultrasonic

Applications

Metering

Flows





Physical principle

various

Applications

PH

Dissolved Oxygen

Chemicals

Nutrients

+ a lot more

Sensors / Water II / Chemistry



Sensors / Air I

Air quality/pollution sensors are an especially complex area

Indoor / outdoor

→ different gases/pollution types of interest

Indoor: CO₂, Volatile Organic Compounds (VOCs), Particulate Matter (PM)

Outdoor: Pollutants widely included in Air Quality Index:

NO₂, SO₂, O₃, PM2.5, PM10

Challenge: low-cost sensors vs. “lab grade sensors”

Citizen science projects: e.g. sensor.community, safecast.org

Rapid progress in new sensor types,

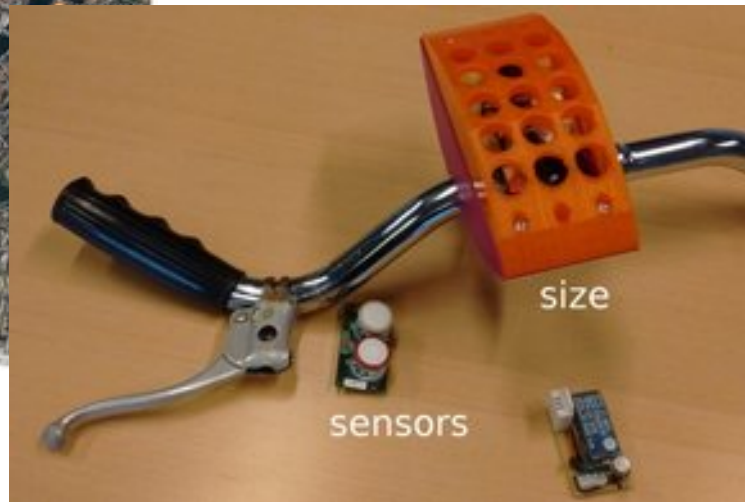
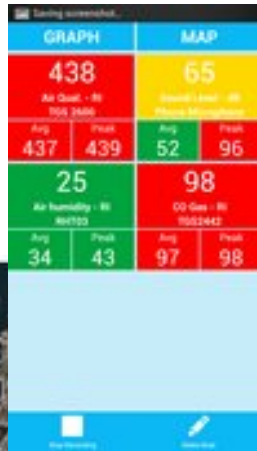
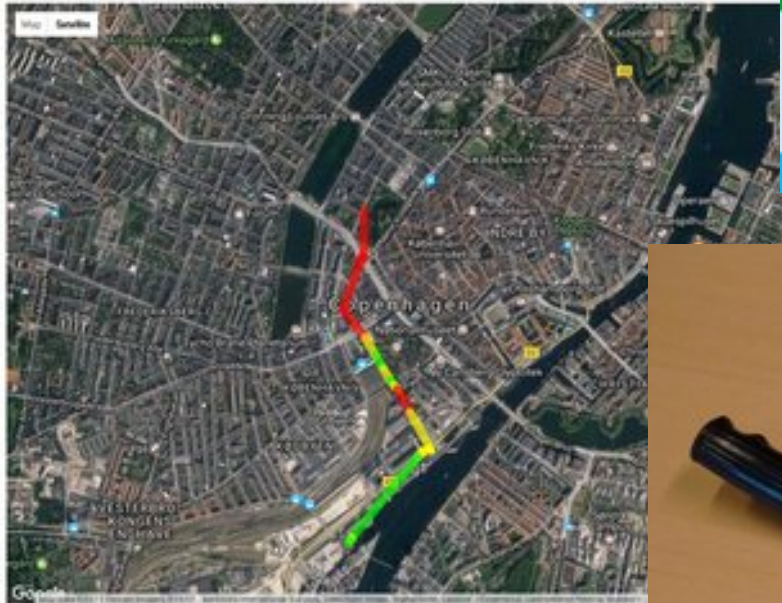
miniature sensors, MEMS, solid state sensors, mobile sensors



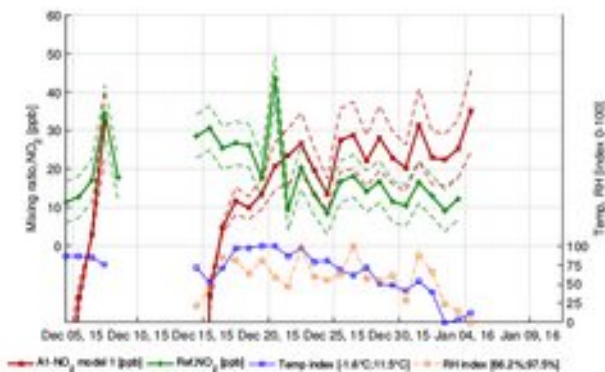
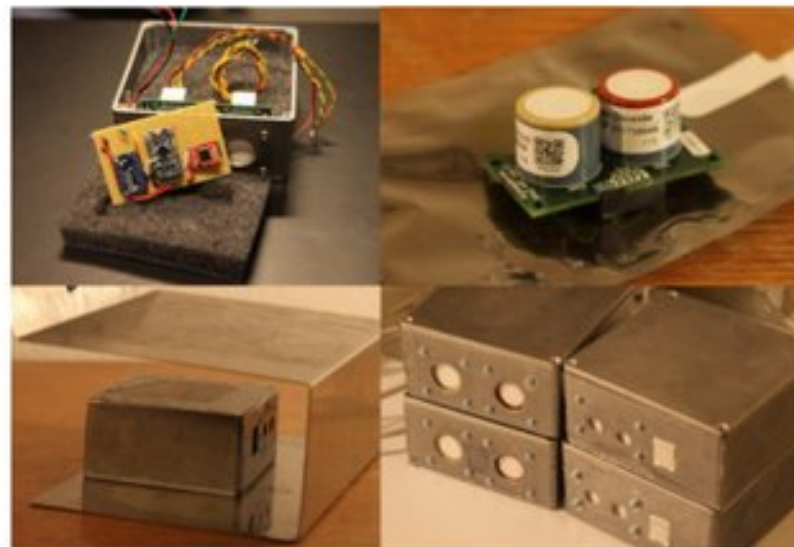
Sensors / Air II



Sensors / "DIY" low cost projects

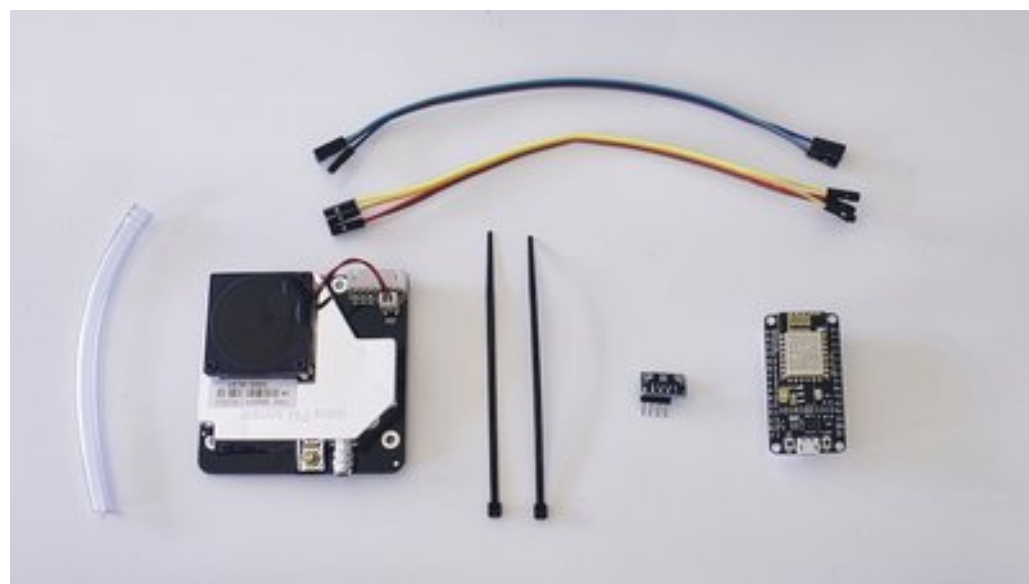


Sensors / low-cost NO₂



Assessing the applicability of low-cost electrochemical gas sensors for urban air quality monitoring

Sensors / citizen science / sensor.community

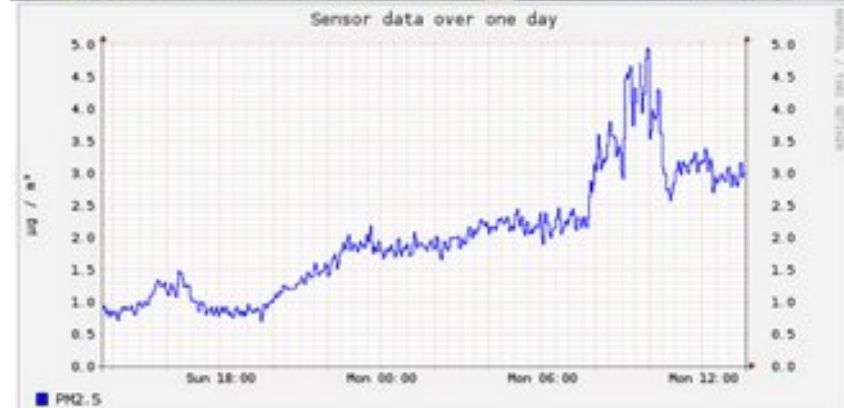


Sensor.Community is a contributors driven global sensor network that creates Open Environmental Data.

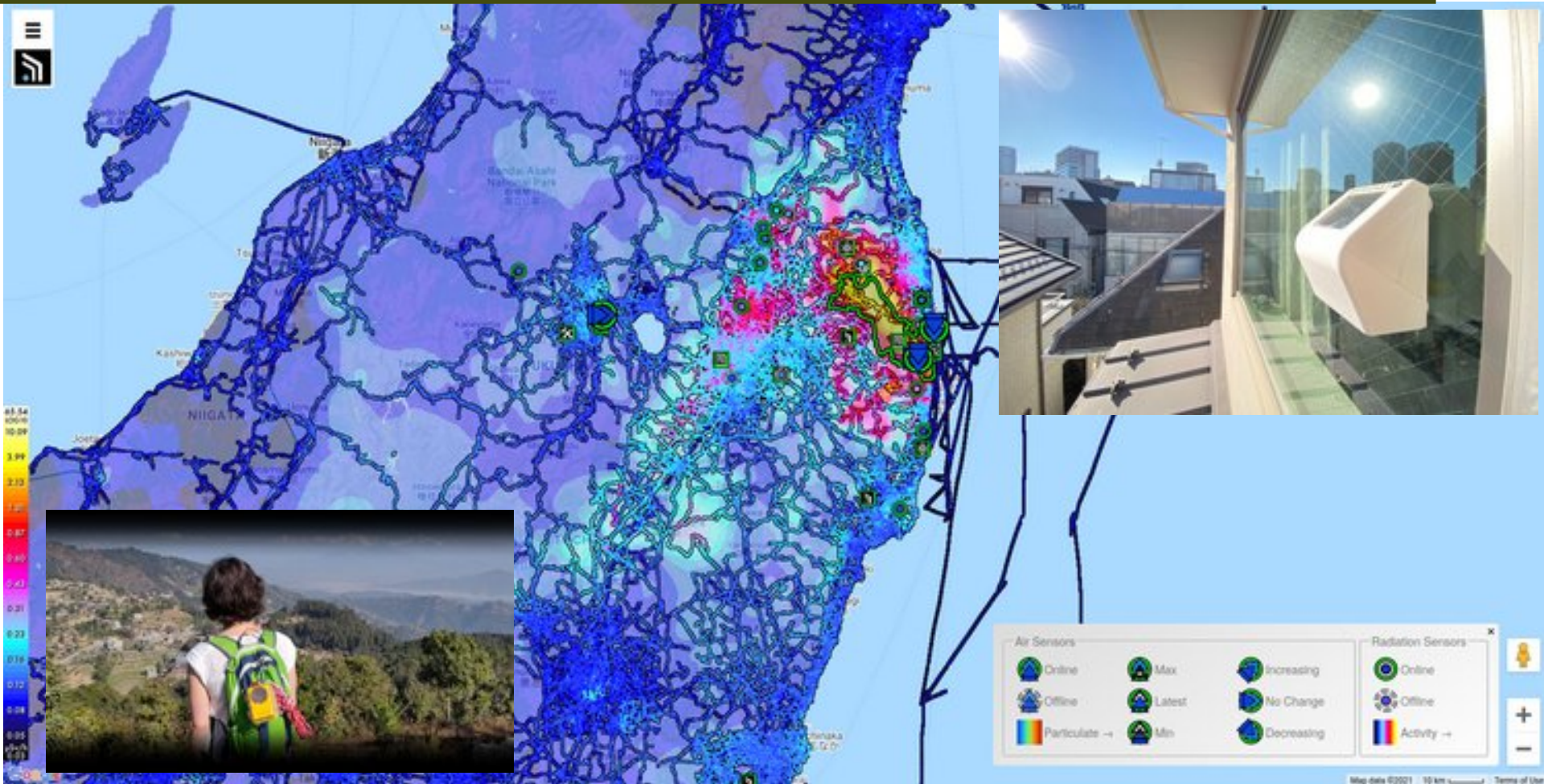
“AirRohr” = the Air tube
sensor: SDS011
board: NodeMCU



source: sensor.community

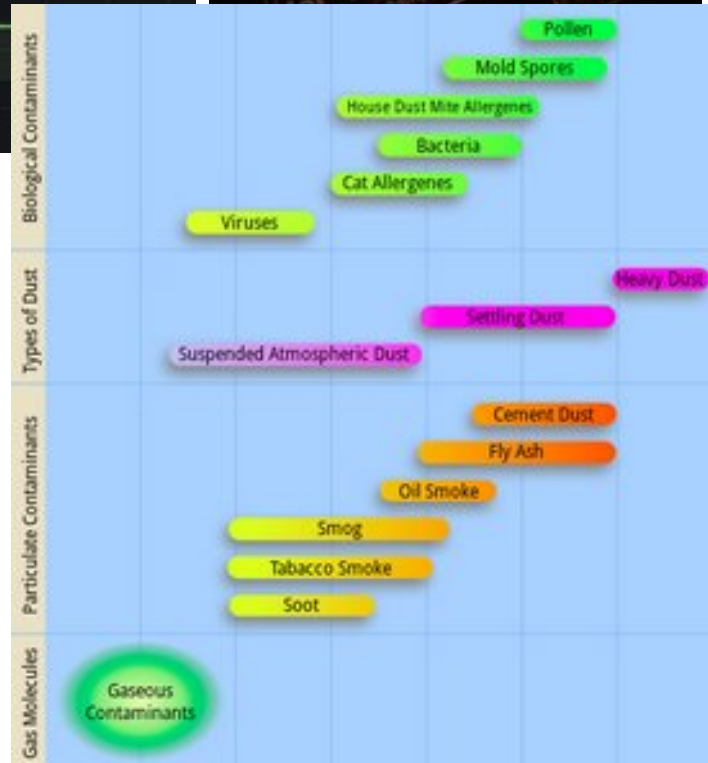


Sensors / citizen science / safecast



check on Twitter!

15 March, 2021
Re-opening of schools
in Germany



Sensors / Cameras, Images, Video

Among all the sensors we named, some were notably **missing**:



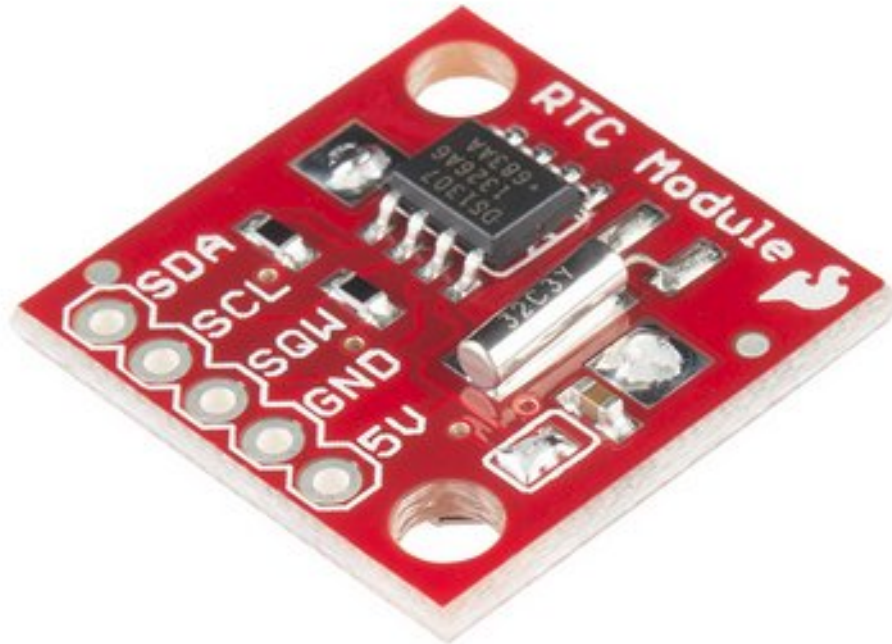
Cameras

perhaps the richest and most popular source for embedded ML

(but are they sensors?

Camera vs Image Sensor?)

Important in all we do: **Time**



for example a **Real Time Clock (RTC)**

(but are they sensors? for discussion ...)

Sensors / Location

Equally important: Location



Physical principle

Data from GNSS Sats

GPS

Glonass

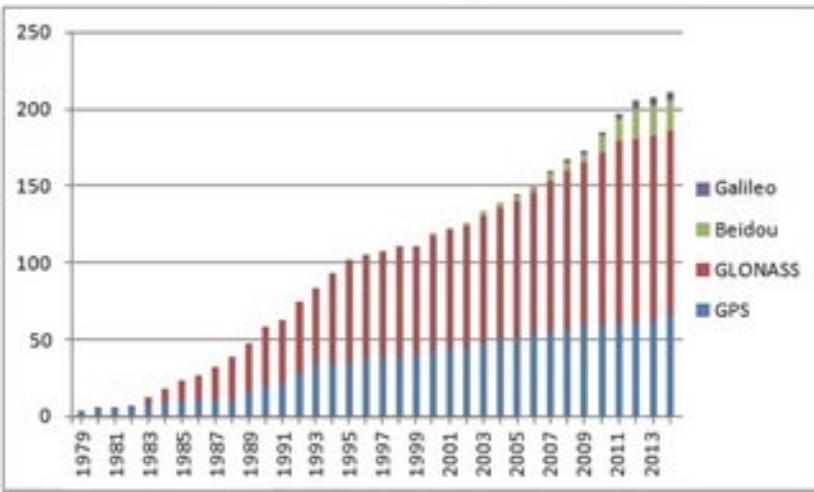
BeiDou

(Is this a sensor?)

Applications

Position

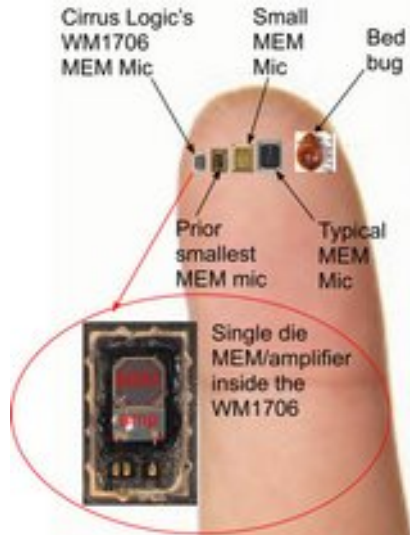
(but are they sensors?)



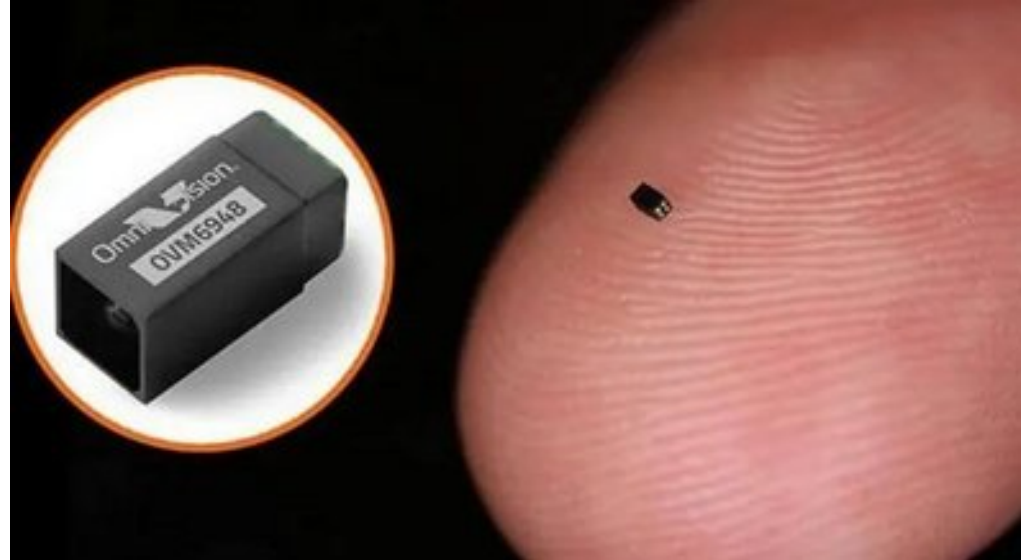
Sensors / Trends, Future

Driven by - among other trends - ,
mobile devices, embedded devices,
IoT, data-centric ML:

MEMS
(micro electro mechanical systems),
nanosensors



age pixels < 1 μm



OmniVision OV6948 *image sensor*

40k (200x200) pixels

0.575 x 0.575 x 0.232mm

Arduino TinyML kit has OV7675 Camera

CirrusLogic WM1706 microphone



Sensors / Trends, Future

Remote sensing from satellite:

Optical & whole EM spectrum

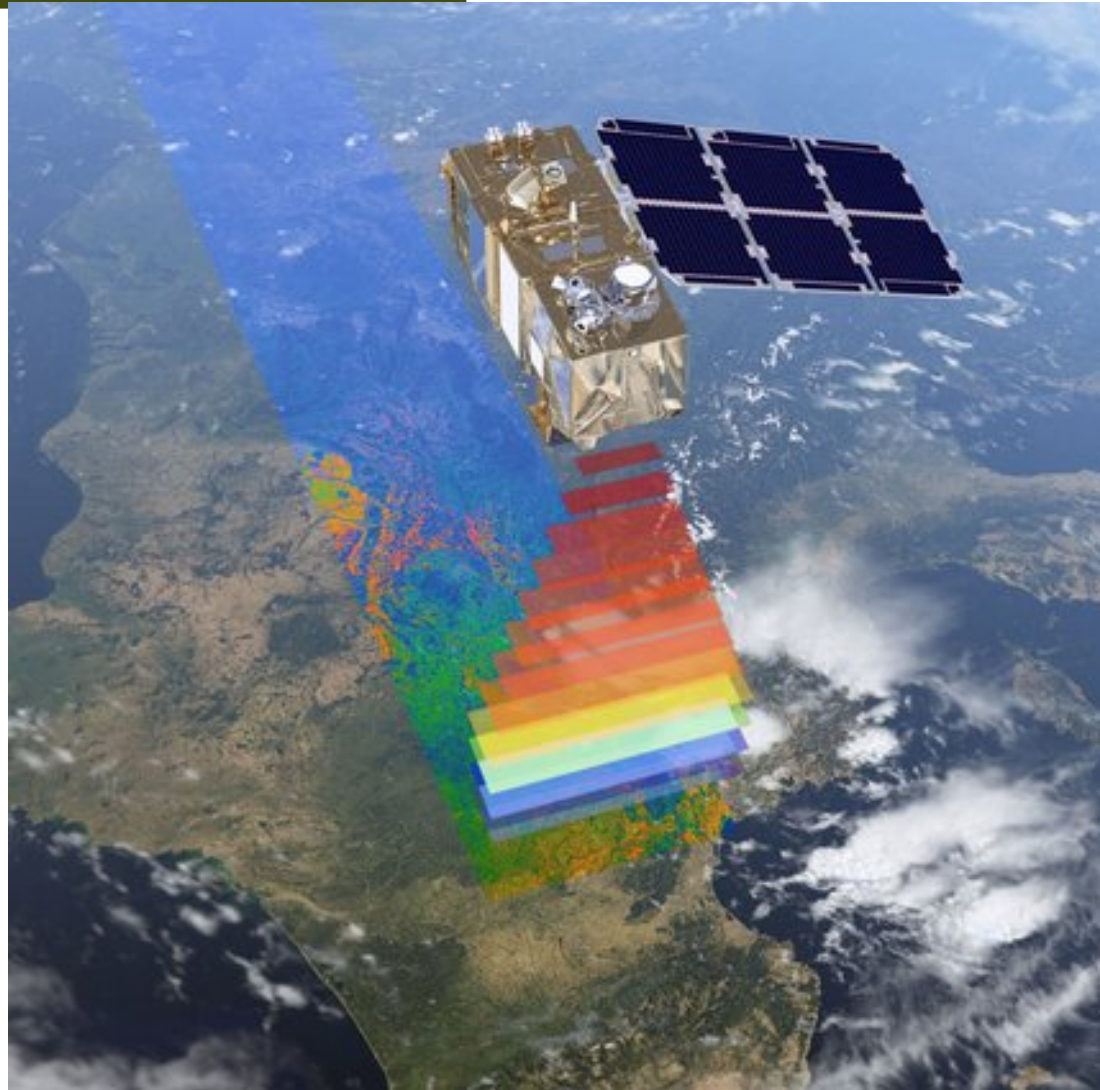
e.g. for

Air quality,

surface,

agriculture,

oceans, ...

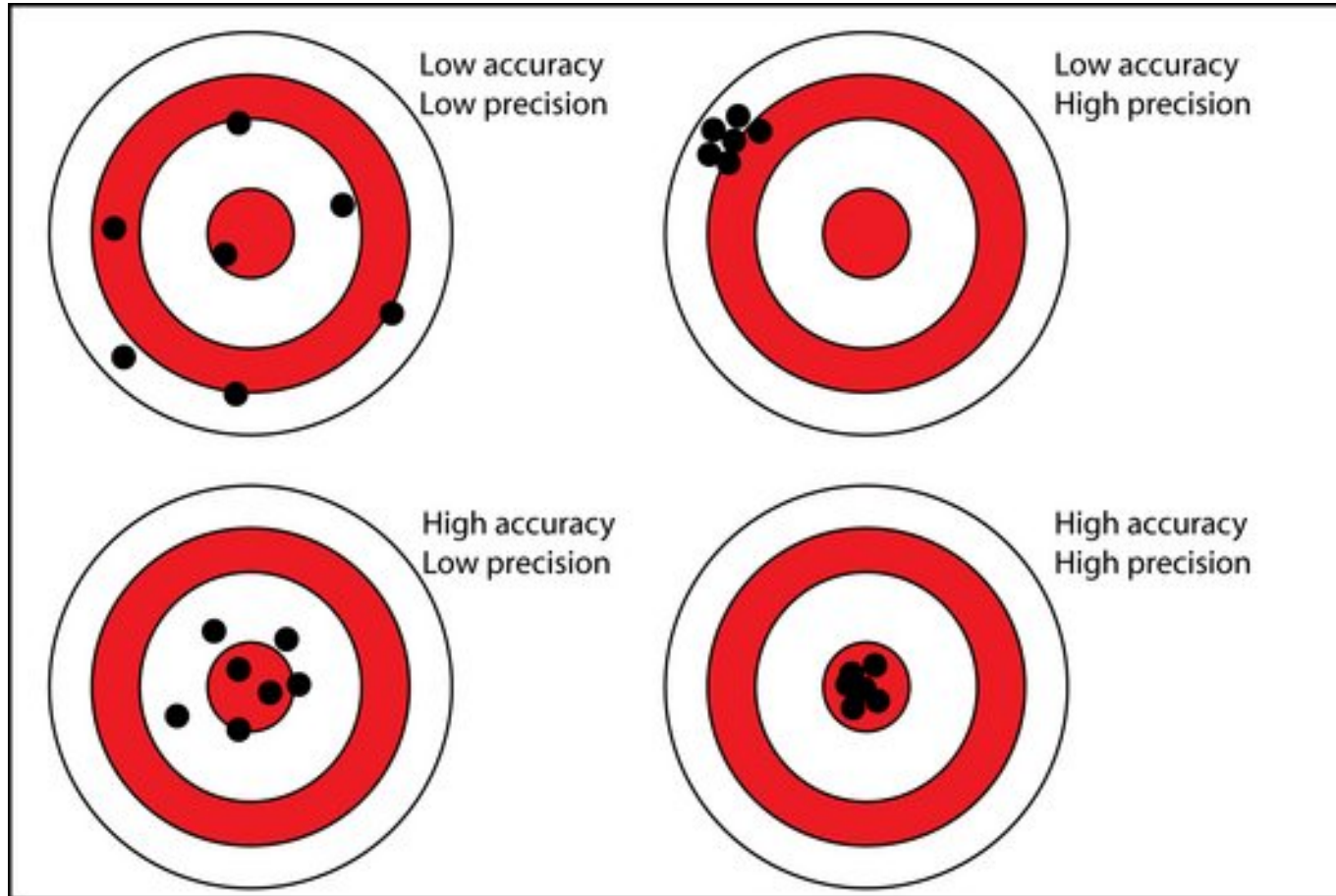


Sensors / Terminology I

- **Sensitivity** – minimum change needed to change output
- **Range** – minimal and maximal values
- **Precision** – spread - ability to give **same** value under same conditions
- **Accuracy** – bias, ability to give **true** value under same conditions
- **Resolution** – minimal difference that can be told apart
- Offset – Bias
- Linearity – over whole range
- Hysteresis – dependence on former history
- Drift – change in offset or behaviour over time
- Response Time – how fast
- Rate – how often

<http://www.ni.com/white-paper/14860/en/>

Sensors / Terminology III / Accuracy & Precision



Sensors / Terminology IIIa / Accuracy & Precision



- Sensors **always require calibration**, and in many cases **frequent re-calibration**
- Might be factory-based and/or performed by user
- Calibration needs to be documented
- Might depend on many variables!

3.7.2 Model 2

Model 2 introduces a linear dependency in the zero offsets on temperature and humidity:

$$Y = \frac{WE - WE_0(a_1T + b_1RH) - (AE - AE_0(a_2T + b_2RH))}{S_T} \quad (3.21)$$

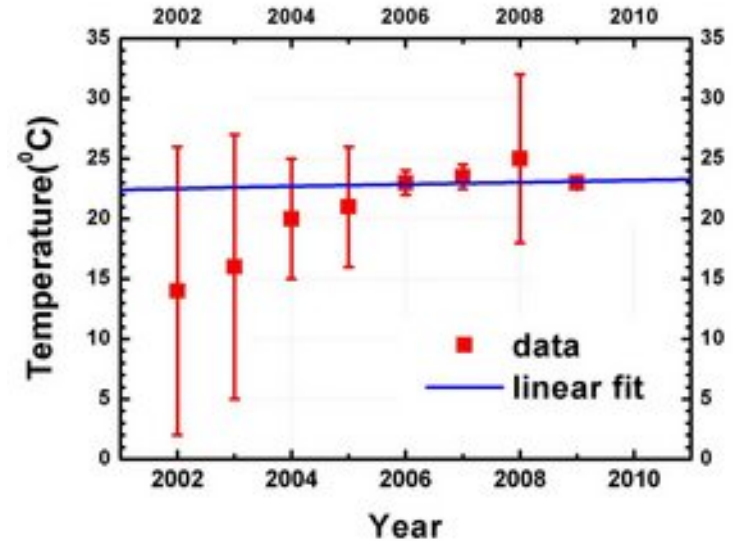
where

a_1 , a_2 , b_1 and b_2 are four parameters obtained from the calibration

T is temperature [K]

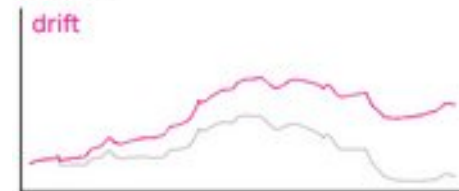
RH is the relative humidity [%]

- Sensors **always** require discussion of errors
- In the physical world, a **measurement without discussion of error is useless**



Sensors fail in many ways ...

- drop out
- flat-lining
- drift
- offset/bias
- noise
- time shift
(loss of time axis - not really a sensor issue)



sensor failures are often hard to detect -
what is an outlier, what is real?

redundant sensors might help

- **Short distance (intra board)**
- **Moderate data rates (kBps)**

Three most popular standards:

- **I²C** (Inter-Integrated Circuit)
- **SPI** (Serial Peripheral Interface)
- **1-Wire**

Sensors / Communication in embedded devices II

- **I²C** (Inter-Integrated Circuit), pronounced I-squared-C, is a synchronous, multi-master, multi-slave, packet switched, single-ended, serial computer bus (1982 Philips Semiconductor, now NXP Semiconductors). Two bidirectional wires: Serial Data Line (SDA) and Serial Clock Line (SCL)
- The Serial Peripheral Interface (**SPI**) is a synchronous serial communication interface specification used for short distance communication, primarily in embedded systems (Motorola, 1980s). 4 wires, full duplex.
- **1-Wire** is a device communications bus system designed by Dallas Semiconductor Corp. that provides low-speed (16.3kbps) data, signaling, and power over a single conductor. Similar in concept to I²C, but with lower data rates and longer range.

- Analog signals require

Analog-to-Digital Conversion

- Rate, Resolution
- ADC and reference voltage need to match signal range, e.g.

A 10-bit ADC with $U_R=5V$ converting a 20 mV signal range will give you no more than 5 discrete values

→ Signal conditioning, Amplification

Sensors / ADC (analog-to-digital conversion)

Analog signals require **Analog-to-Digital Conversion**

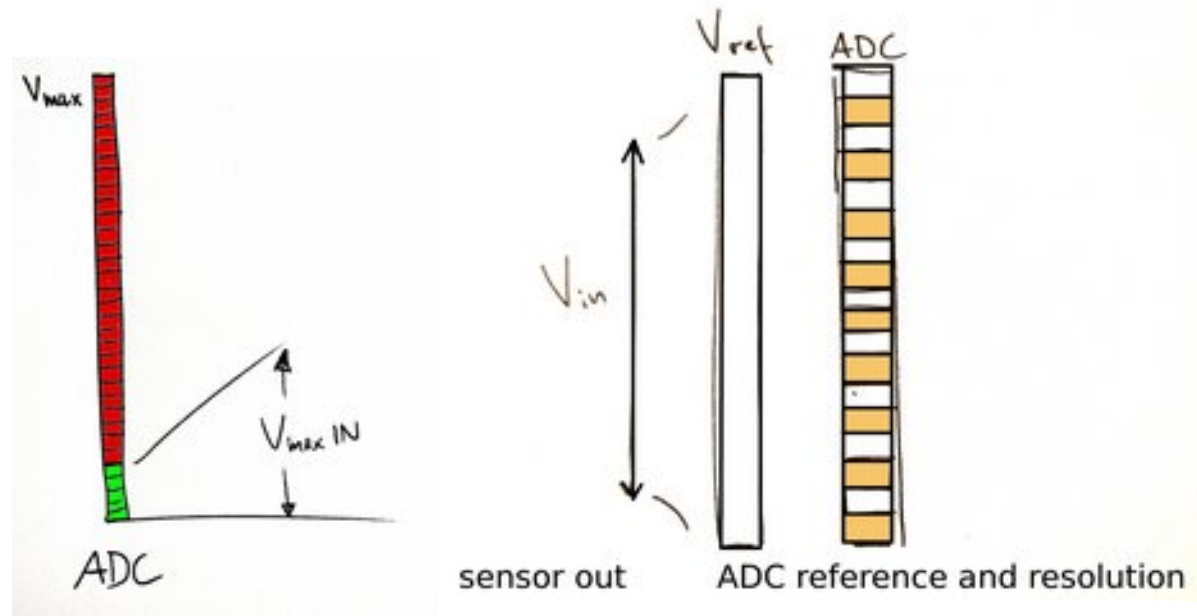
(Rate [kHz], Resolution [bits])

ADC and reference voltage need to match signal range,

else resolution remains unused -

→ Signal conditioning,

Amplification



- Find the datasheet (and know how to read it!)

Datasheet Sensirion SCD30 Sensor Module

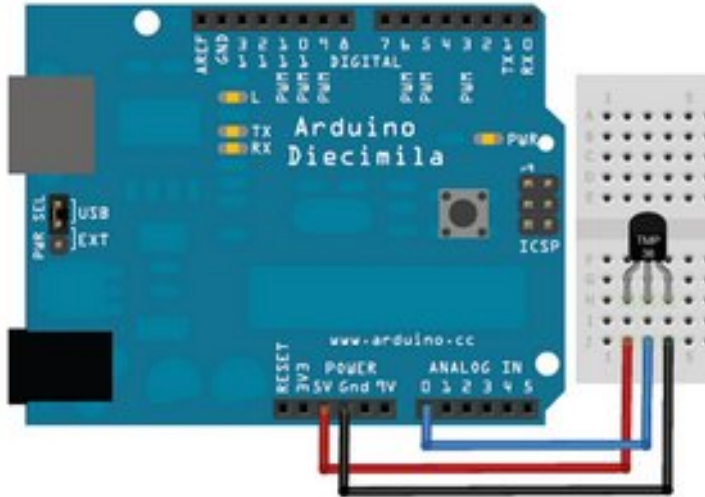
CO₂, humidity, and temperature sensor

- NDIR CO₂ sensor technology
- Integrated temperature and humidity sensor
- Best performance-to-price ratio
- Dual-channel detection for superior stability
- Small form factor: 35 mm x 23 mm x 7 mm
- Measurement range: 400 ppm – 10.000 ppm
- Accuracy: $\pm(30 \text{ ppm} + 3\%)$
- Current consumption: 19 mA @ 1 meas. per 2 s.
- Fully calibrated and linearized
- Digital interface UART or I²C



Sensors / Practical Advice

- Find “hookup” guides, applications notes
- Find existing libraries for your platform
- decoders, calibration routines, etc



```
import time
from machine import I2C, Pin
from scd30 import SCD30

i2cbus = I2C(1)
scd30 = SCD30(i2c, 0x61)
```


Sensors / Use Case Utility Meters Retrofitting

technologies:

Wemos/Lolin boards,
LoRa or Wi-Fi

benefit:

fine-grained
consumption data



Note: this is legal (in Denmark),
but **not necessarily recommended** for copying! :)

Sensors / Use Case Utility Meters Retrofitting

ITU

Residential Electricity



https://www.wemos.cc/en/latest/d1/d1_mini.html

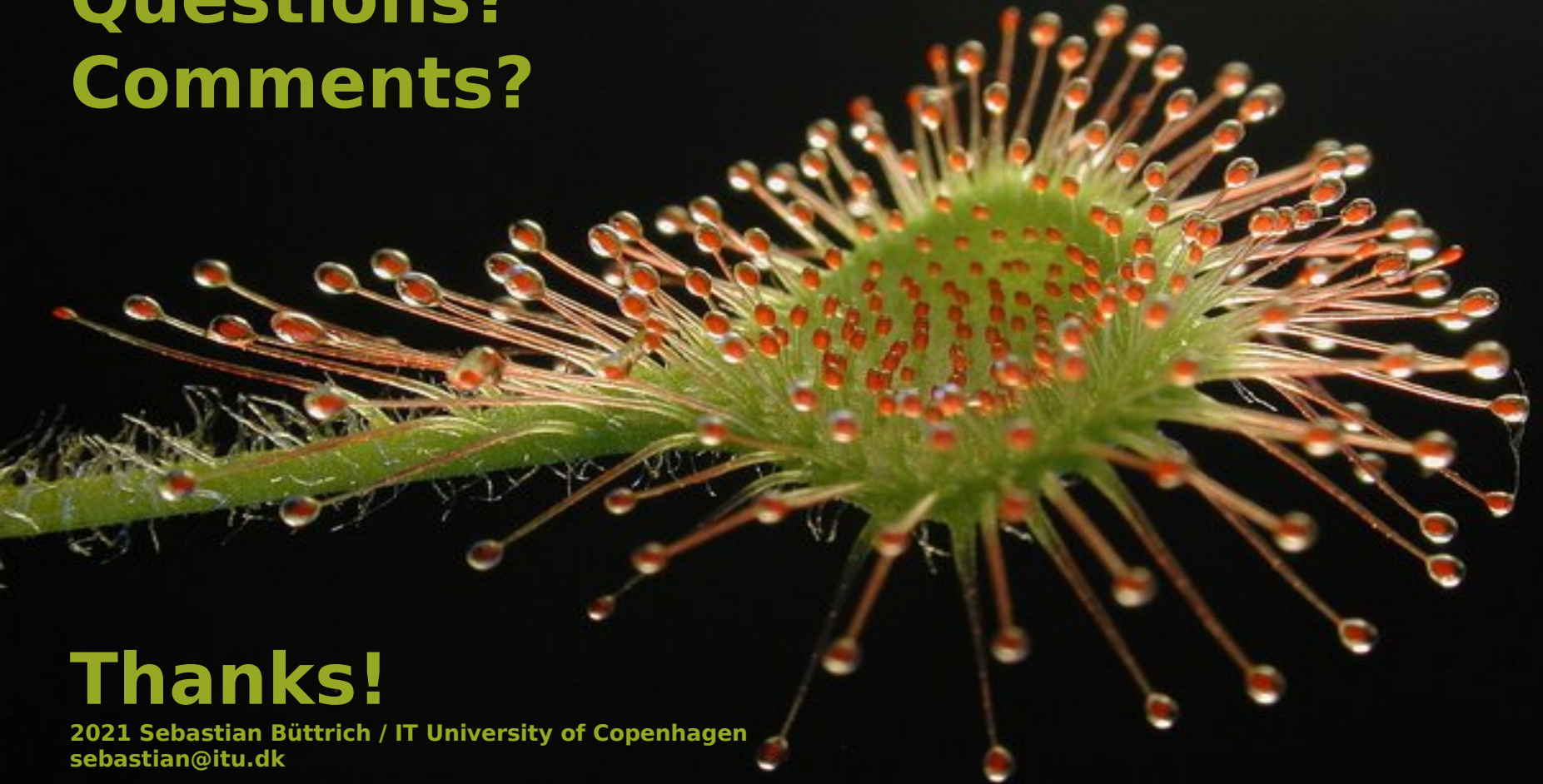
Sensors / Use Case CO₂ at lab



Sensors / Use Case CO₂ at home



**Questions?
Comments?**



Thanks!

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